

# Graph Theory

## [6]

Maximum flows  
Ford-Fulkerson method  
Edmonds and Karp's algorithm

*Documents are here:*



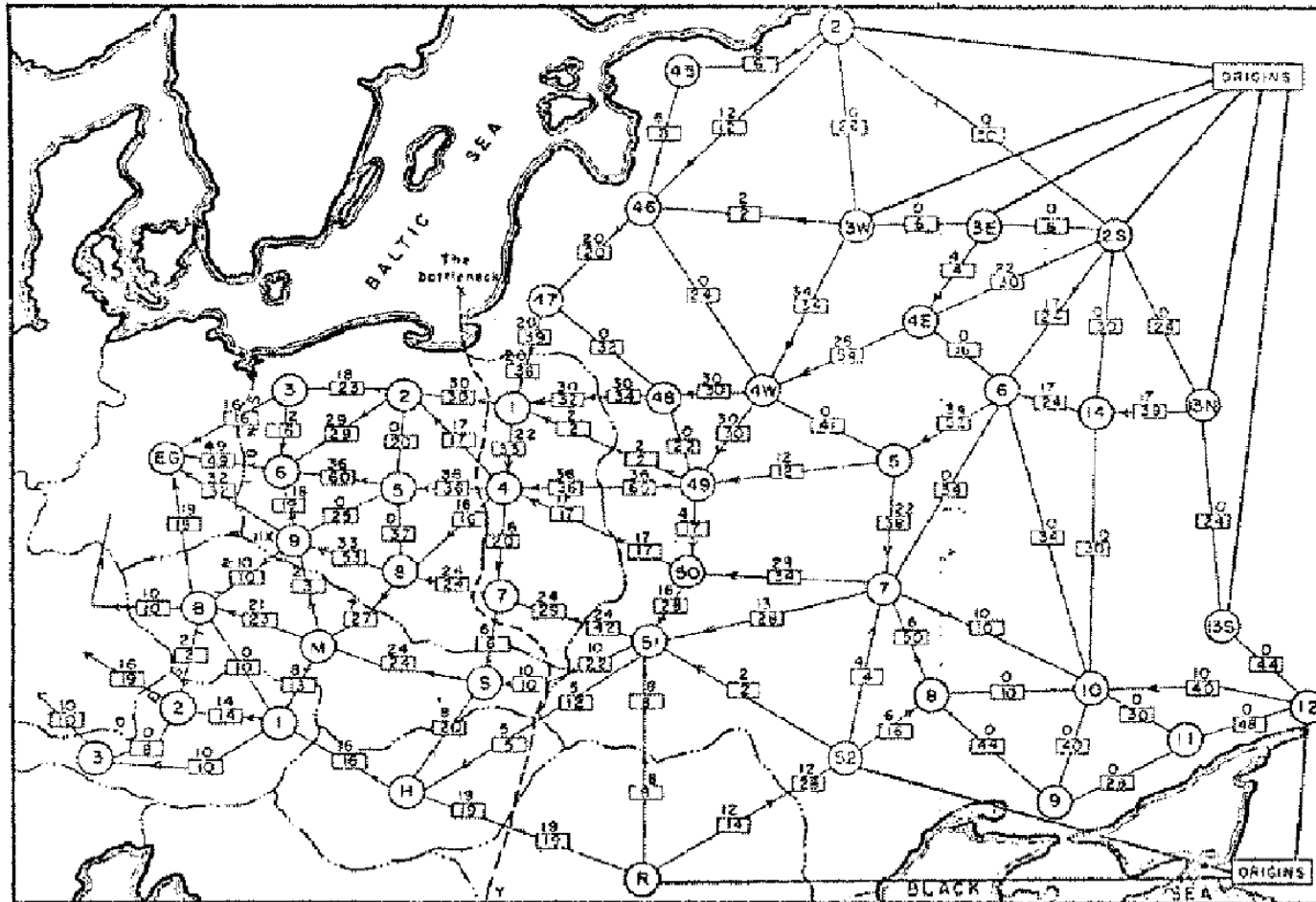
<https://www-l2ti.univ-paris13.fr/~viennet/ens/2024-USTH-Graphs>

*Emmanuel Viennet*

[emmanuel.viennet@univ-paris13.fr](mailto:emmanuel.viennet@univ-paris13.fr)



# Soviet Rail Network, 1955

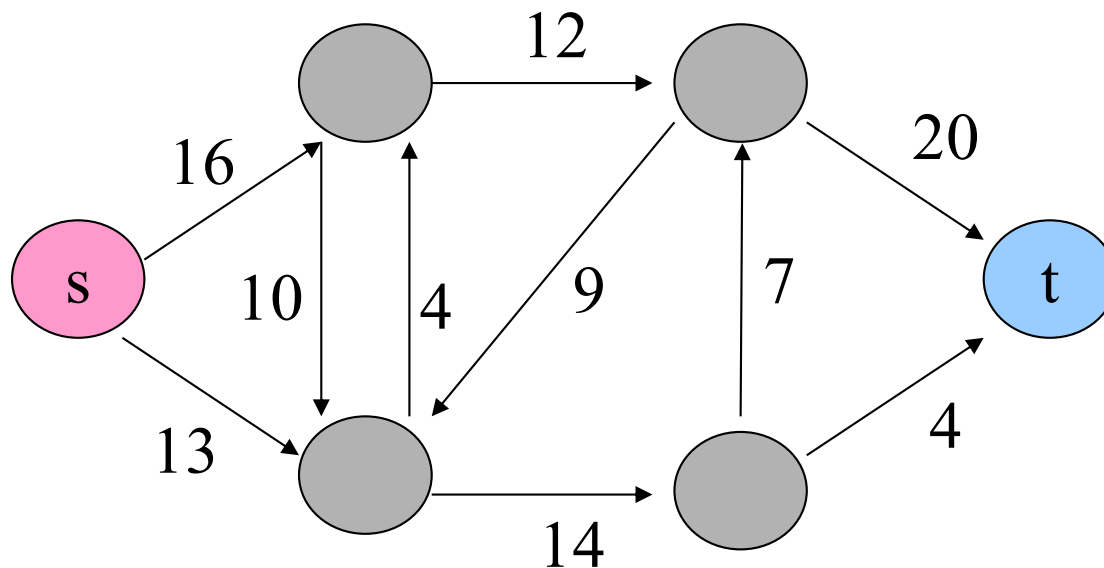


Reference: *On the history of the transportation and maximum flow problems.*  
Alexander Schrijver in *Math Programming*, 91: 3, 2002.

•material coursing through a system from a source to a sink

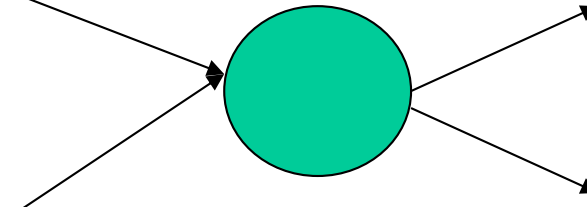
# Flow networks:

- A **flow network**  $G=(V,E)$ : a directed graph, where each edge  $(u,v) \in E$  has a nonnegative **capacity**  $c(u,v) \geq 0$ .
- If  $(u,v) \notin E$ , we assume that  $c(u,v)=0$ .
- two distinct vertices :a **source**  $s$  and a **sink**  $t$ .



# Flow:

- $G=(V,E)$ : a flow network with capacity function  $c$ .
- $s$ -- the source and  $t$ -- the sink.
- A flow in  $G$ : a real-valued function  $f:V*V \rightarrow \mathbb{R}$  satisfying the following three properties:
- **Capacity constraint**: For all  $u,v \in V$ ,  
we require  $f(u,v) \leq c(u,v)$ .
- **Flow conservation**: For all  $u \in V-\{s,t\}$ , we require

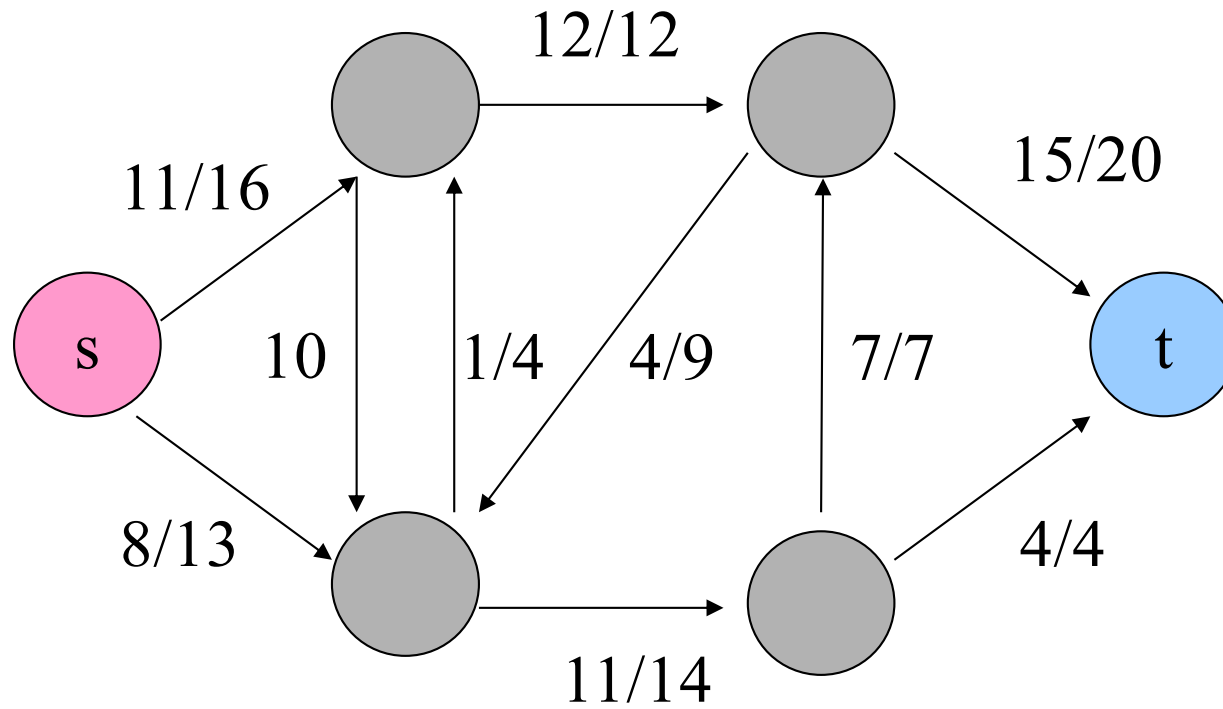
$$\sum_{e.in.v} f(e) = \sum_{e.out.v} f(e)$$


# Net flow and value of a flow $f$ :

- The quantity  $f(u, v)$ , which can be positive or negative, is called the **net flow** from vertex  $u$  to vertex  $v$ .
- The **value** of a flow is defined as

$$|f| = \sum_{v \in V} f(s, v)$$

- The total flow from source to any other vertices.
- The same as the total flow from any vertices to **the sink**.



A flow  $f$  in  $G$  with value  $|f| = 19$  .

# Maximum-flow problem:

- Given a flow network  $G$  with source  $s$  and sink  $t$
- **Find a flow of maximum value** from  $s$  to  $t$ .
- How to solve it efficiently?



# The Ford-Fulkerson method

This section presents the Ford-Fulkerson method for solving the maximum-flow problem. We call it a “method” rather than an “algorithm” because it encompasses several implementations with different running times.

The Ford-Fulkerson method depends on three important ideas that transcend the method and are relevant to many flow algorithms and problems: [residual networks](#), [augmenting paths](#), and [cuts](#).

These ideas are essential to the important max-flow min-cut theorem, which characterizes the value of maximum flow in terms of cuts of the flow network.



# The Ford-Fulkerson method

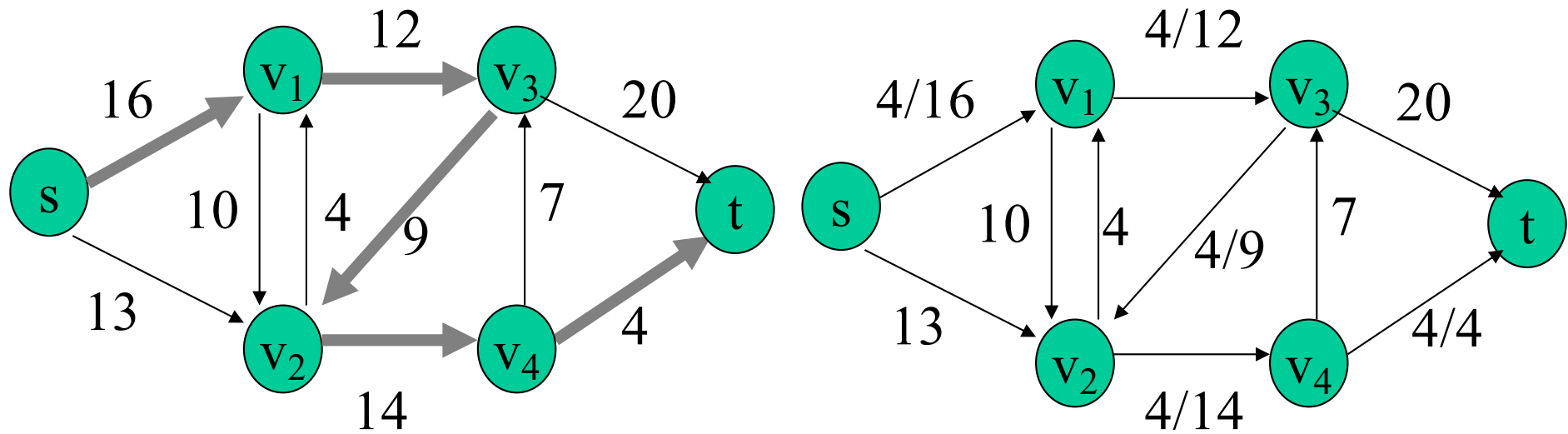
Given a graph  $G$  and two nodes  $(s, t)$

- initialize flow  $f$  to  $0$
- **while** there exists an *augmenting* path  $p$
- **do** *augment* flow  $f$  along  $p$
- return  $f$

# Residual networks

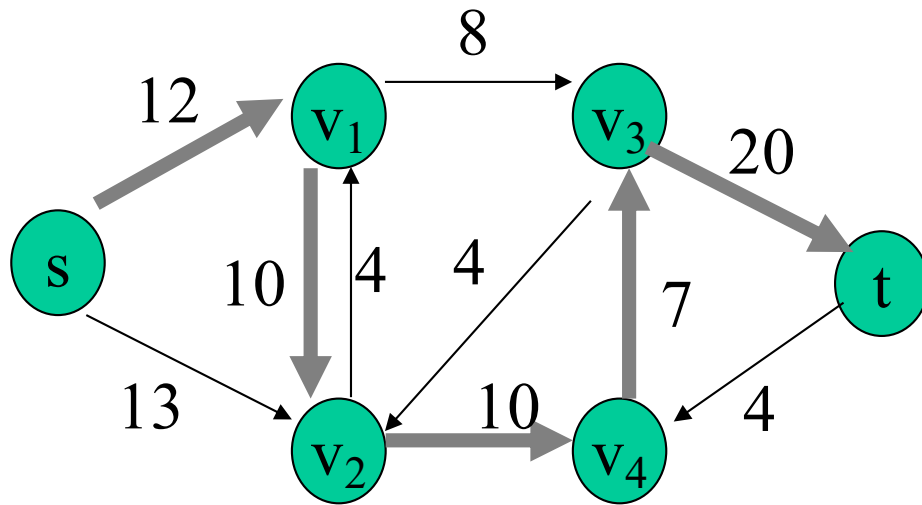
- Given a flow network and a flow, the **residual network** consists of edges that can admit more net flow.
- $G=(V, E)$  a flow network with source  $s$  and sink  $t$
- $f$ : a flow in  $G$ .
- The amount of additional net flow from  $u$  to  $v$  before exceeding the capacity  $c(u,v)$  is the **residual capacity** of  $(u,v)$ , given by:  $c_f(u,v) = c(u,v) - f(u,v)$

## Example of residual network



(a)

## Example of Residual network (continued)



(b)

# Fact 1

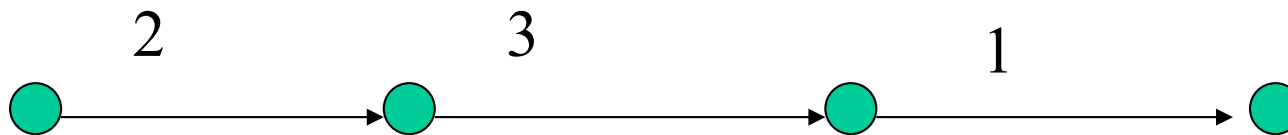
- Let  $G=(V,E)$  be a flow network with source  $s$  and sink  $t$ , and let  $f$  be a flow in  $G$
- Let  $G_f$  be the residual network of  $G$  induced by  $f$ , and let  $f'$  be a flow in  $G_f$

Then, the flow sum  $f+f'$  is a flow in  $G$  with value

$$|f + f'| = |f| + |f'|$$

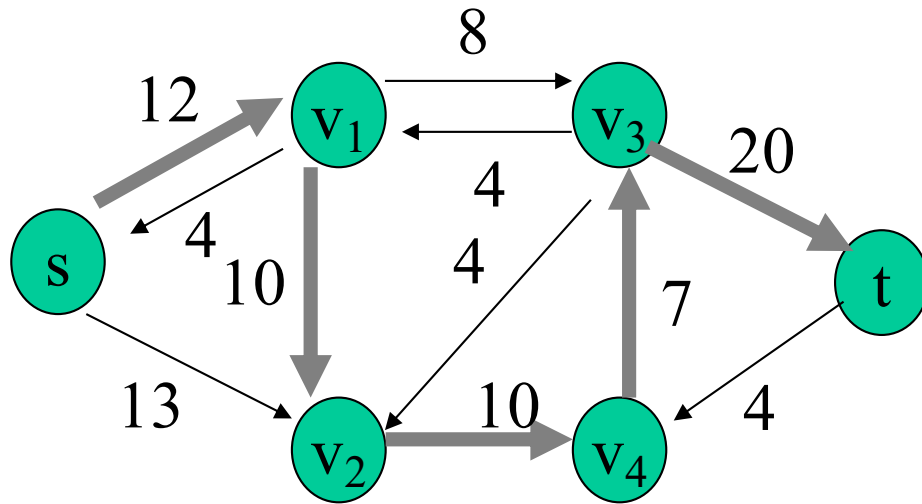
# Augmenting paths

- Given a flow network  $G=(V,E)$  and a flow  $f$ , an **augmenting path** is a simple path from  $s$  to  $t$  in the residual network  $G_f$ .
- **Residual capacity** of  $p$  : the maximum amount of net flow that we can ship along the edges of an augmenting path  $p$ , i.e.,  $c_f(p)=\min\{c_f(u,v):(u,v) \text{ is on } p\}$ .



*The residual capacity is 1*

## Example of an augment path (bold edges)



(b)

# The basic Ford-Fulkerson algorithm:

- FORD-FULKERSON( $G,s,t$ )
- **for** each edge  $(u,v) \in E[G]$
- **do**  $f[u,v] \leftarrow 0$
- $f[v,u] \leftarrow 0$
- **while** there exists a path  $p$  from  $s$  to  $t$  in the residual network  $G_f$
- **do**  $c_f(p) \leftarrow \min\{c_f(u,v): (u,v) \text{ is in } p\}$
- **for** each edge  $(u,v)$  in  $p$
- **do**  $f[u,v] \leftarrow f[u,v] + c_f(p)$
-



# Example: next slides (a) to (e)

Execution of the basic Ford-Fulkerson algorithm (successive iterations of the **while** loop)

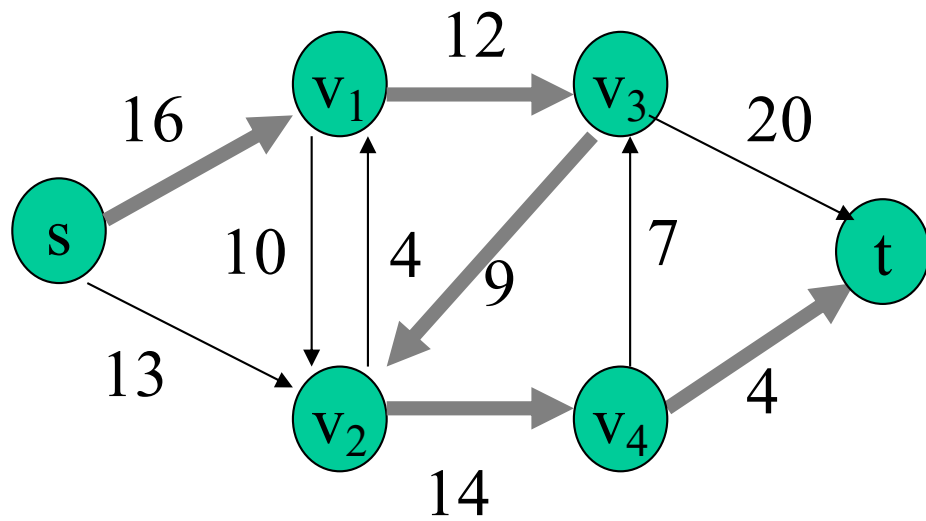
The **left side** of each part shows the **residual network**  $G_f$  with a shaded augmenting path  $p$ .

The **right side** of each part shows the **new flow**  $f$  that results from adding  $f_p$  to  $f$ .

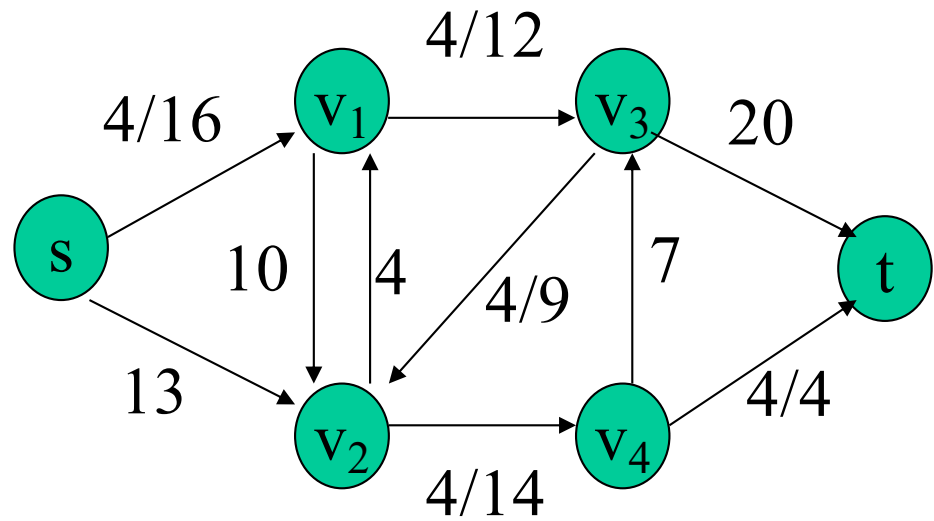
The residual network in (a) is the input network  $G$ .

(e) The residual network at the last **while** loop test. It has no augmenting paths, and the flow  $f$  shown in (d) is therefore a maximum flow.

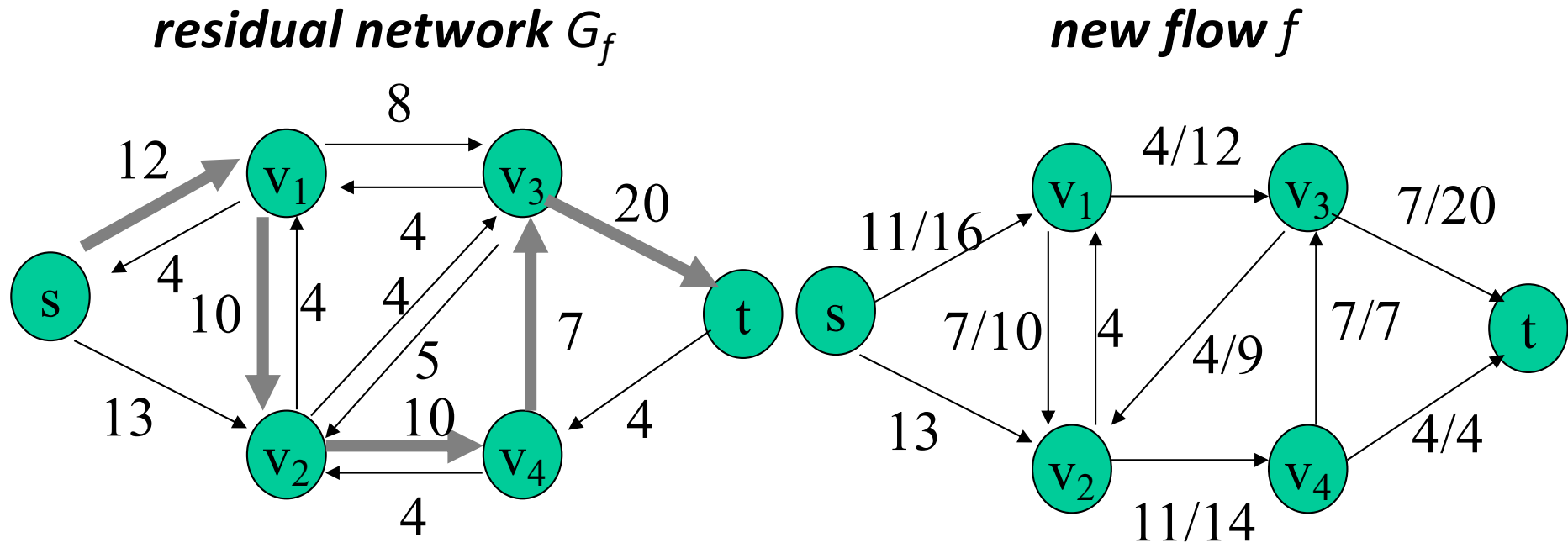
*residual network  $G_f$*



*new flow  $f$*

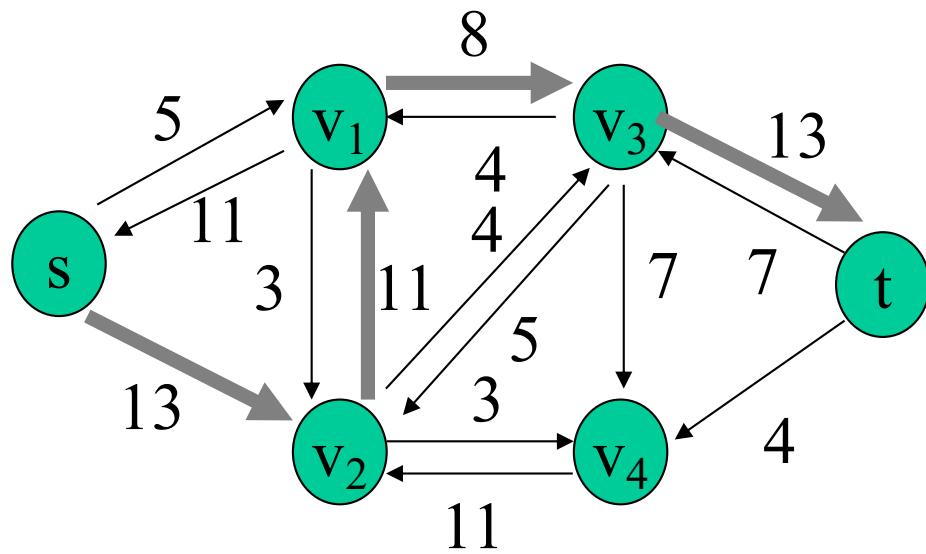


(a)

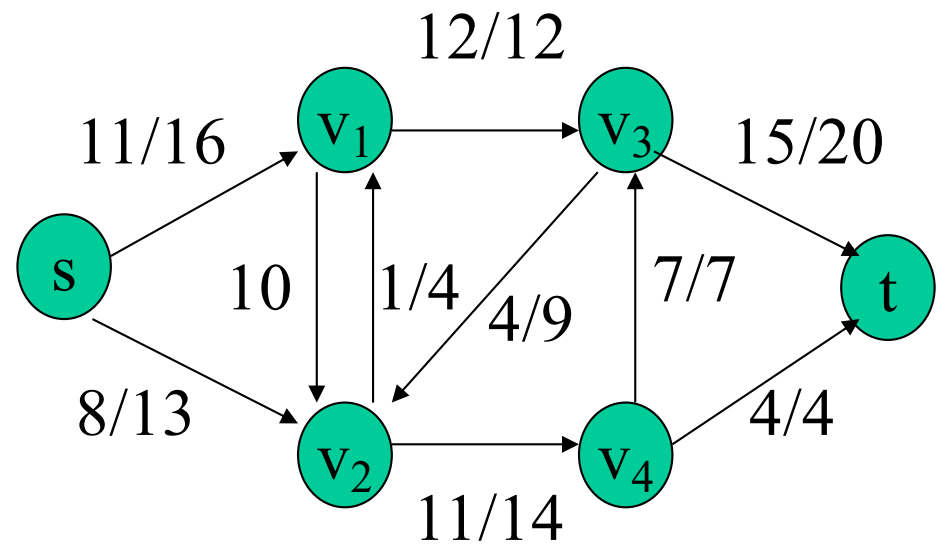


(b)

*residual network  $G_f$*

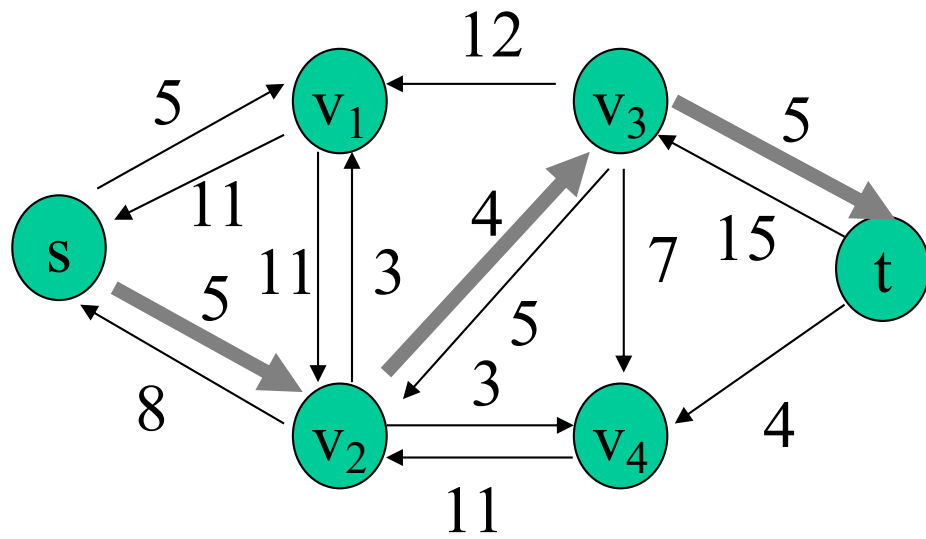


*new flow  $f$*

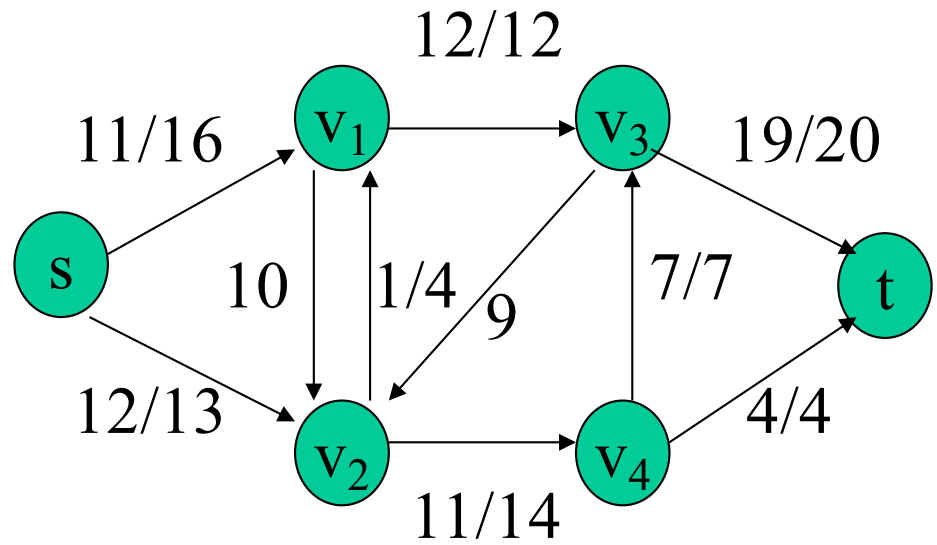


(c)

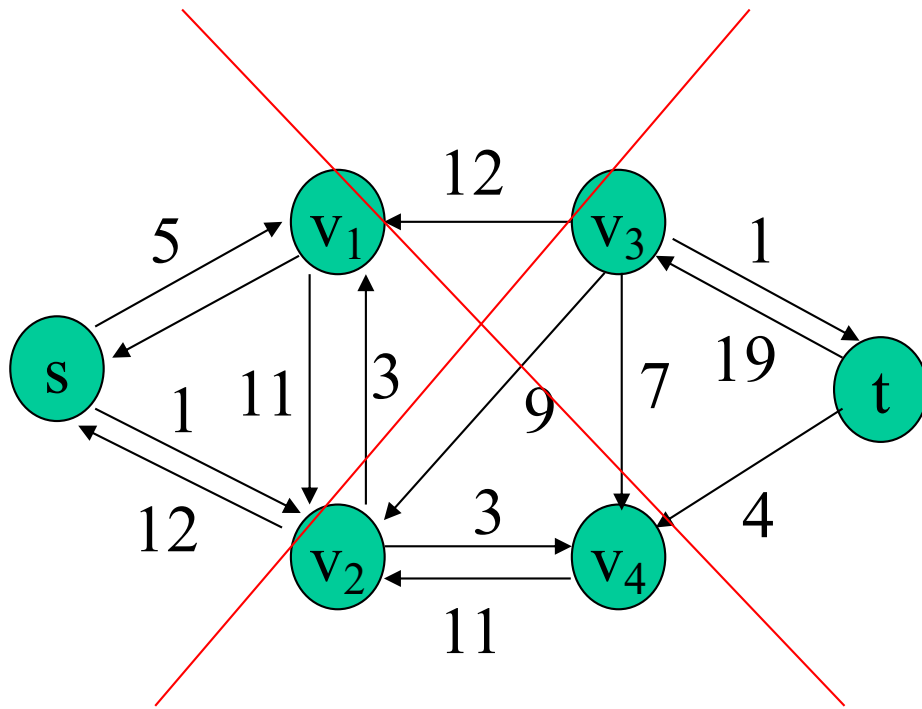
*residual network  $G_f$*



*new flow  $f$*



(d)



No augmenting path !  
**stop**

(e)

# Time complexity

Time complexity of the Ford-Fulkerson's algorithm is

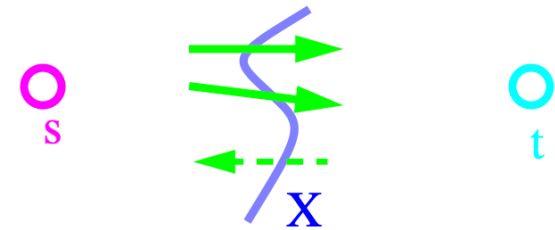
$$O(\text{max\_flow} * E)$$

We run a loop while there is an augmenting path.

In worst case, we may add 1 unit flow in every iteration.

Therefore the time complexity becomes  $O(\text{max\_flow} * E)$ .

# Cuts of flow networks

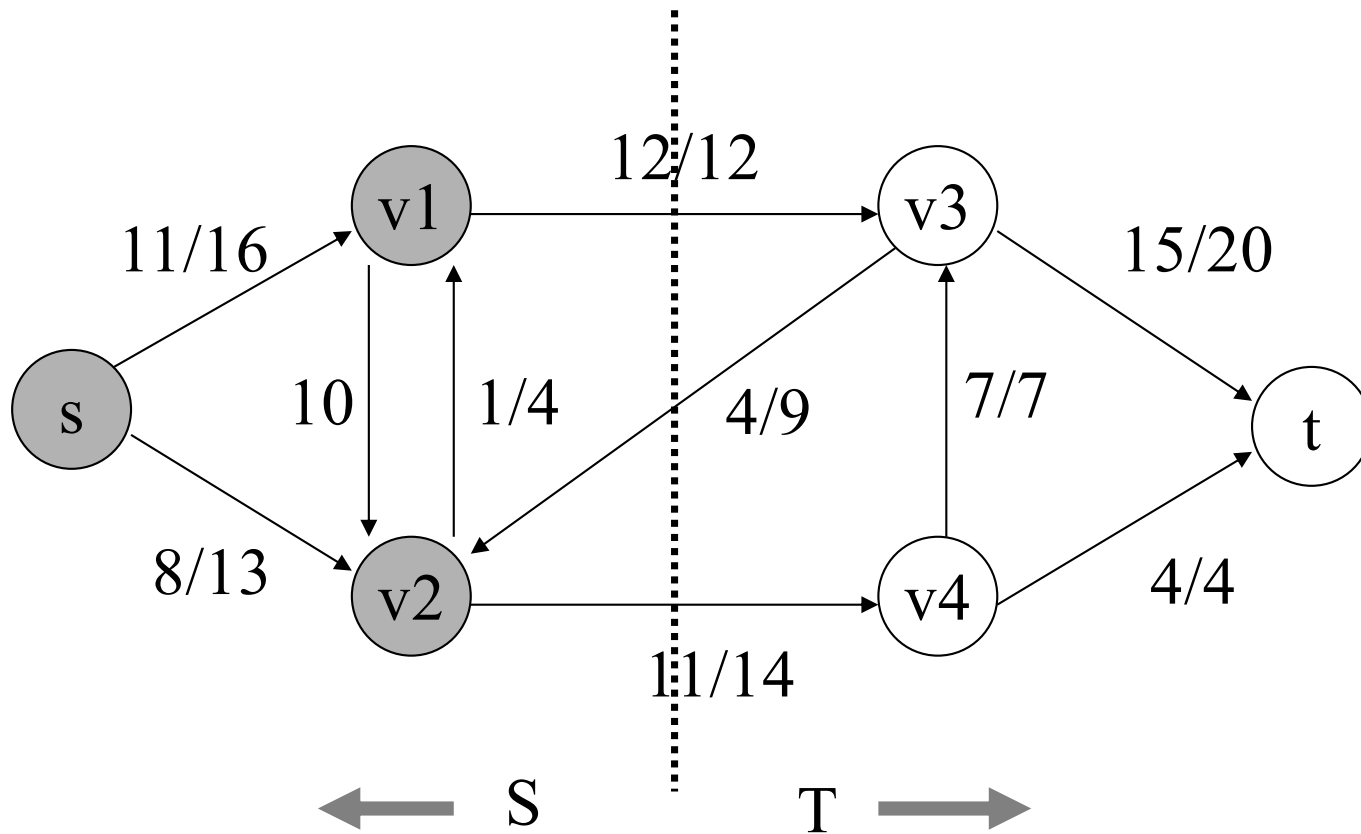


The proof of the correctness of the Ford-Fulkerson method depends on a concept “cut”.

- A **cut**  $(S,T)$  of flow network  $G=(V,E)$  is a partition of  $V$  into  $S$  and  $T=V-S$  such that  $s \in S$  and  $t \in T$ .
- If  $f$  is a flow, then the net flow across the cut  $(S,T)$  is  $F(S,T)=\sum_{u \in S \& v \in T} f(u, v)$ .
- The capacity of the cut  $(S,T)$  is

$$c(S, T)=\sum_{u \in S \& v \in T} c(u, v).$$





A cut  $(S, T)$ , where  $S = \{s, v_1, v_2\}$  and  $T = \{v_3, v_4, t\}$ .

The net flow across  $(S, T)$  is  $f(S, T) = 12 - 4 + 11 = 19$

and the capacity is  $c(S, T) = 12 + 14 = 26$ .

# Property of cuts

- Let  $f$  be a flow in a flow network  $G$  with source  $s$  and sink  $t$ , and let  $(S, T)$  be a cut of  $G$ .

Then, the net flow across  $(S, T)$  is  $f(S, T) = |f|$  .

- Proof: 1.  $f(S-s, V) = 0$  by flow conservation.
- 2.  $f(S, S) = 0$  since  $f(u, v) = -f(v, u)$ .
- $f(S, T) = f(S, V) - f(S, S) = f(S, V)$   
 $= f(s, V) + f(S-s, V) = f(s, V) = |f|$ .

# Property of cuts (cont.)

- The value of any flow  $f$  in a flow network  $G$  is bounded from above by the capacity of any cut of  $G$ .
- Proof:  $f(S, T) \leq c(S, T)$ .

## Max-flow min-cut theorem

If  $f$  is a flow in a flow network  $G=(V,E)$  with source  $s$  and sink  $t$ , then the following conditions are equivalent:

1.  $f$  is a maximum flow in  $G$ ;
2. The residual network  $G_f$  contains no augmenting paths;
3.  $|f| = c(S,T)$  for some cut  $(S,T)$  of  $G$ .

### Proof:

1  $\rightarrow$  2: Otherwise, if a aug. path exists, we can further increase the flow.

2  $\rightarrow$  3. If no aug. path exists, then we construct  $S$  as the set of vertices that is reachable from  $s$ .  $T=V-S$ . By construction, there is no edge  $(u, v)$  in the residual graph such that  $u \in S$  and  $v \in T$ . Thus,  $|f| = f(S,T) = c(S, T)$ .

3  $\rightarrow$  1  $|f| = f(S, T) = c(S,T)$ . Recall that  $|f| = f(S, T) \leq c(S,T)$ . Thus,  $|f|$  is maximum.

# The Edmonds-Karp algorithm

- Find the augmenting path using **breadth-first search** (BFS)

Breadth-first search gives the shortest path for graphs (Assuming the length of each edge is 1.)

- Time complexity of Edmonds-Karp algorithm is  $O(VE^2)$ .

Playground:

<https://visualgo.net/en/maxflow>

More examples:

<https://www.hackerearth.com/practice/algorithms/graphs/maximum-flow/tutorial>