

Non-Linear Discriminant Analysis

Gaston BAUDAT, Fatiha ANOUAR

**MEI, Mars Electronics International
1301 Wilson Drive, West Chester, PA 19380, USA**

Email: gaston.baudat@eu.effem.com

Phone: + 1 610 430 27 51

Email: fatiha.anouar@effem.com

Phone: + 1 610 430 25 22

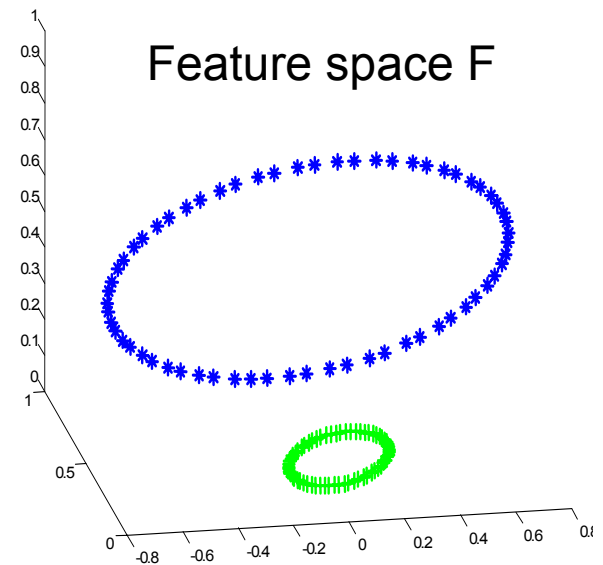
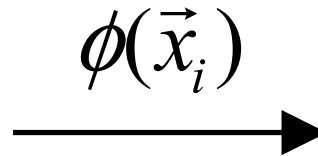
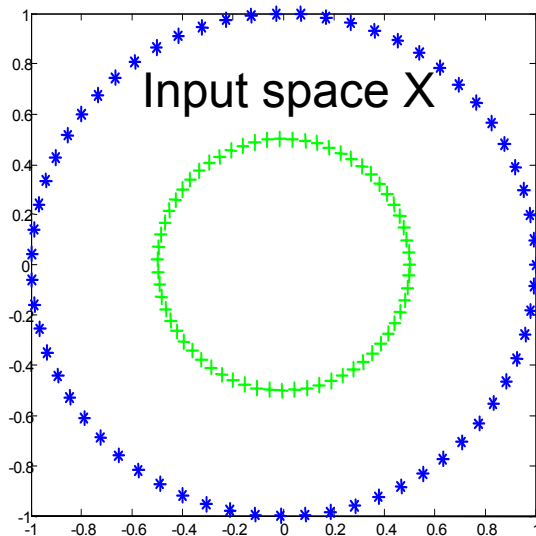
Fax: + 1 610 430 27 95

Presentation plan

- ➔ Kernel Trick
- ➔ Linear Discriminant Analysis (LDA).
- ➔ Generalized Discriminant Analysis (GDA).
- ➔ Feature Vector Selection (FVS).
- ➔ Sparse GDA using the FVS approach.
- ➔ Conclusions.
- ➔ Some references.

Kernel trick & dot product

- Let $\phi(\vec{x}_i)$ be an operator which maps data from an input space X into a feature space F :



Kernel trick & dot product

Ex: Polynomial mapping

- As an example assume the following mapping (2D \rightarrow 3D):

$$\phi(\vec{x}) = \begin{pmatrix} \varphi_{x,1} \\ \varphi_{x,2} \\ \varphi_{x,3} \end{pmatrix} = \begin{pmatrix} x_1^2 \\ x_2^2 \\ \sqrt{2} \cdot x_1 \cdot x_2 \end{pmatrix} \quad \vec{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

Kernel trick & dot product

Ex: Dot product in F

- Explicit dot product in F:

$$\phi^T(\vec{x}) \cdot \phi(\vec{y}) = \varphi_{x,1}\varphi_{y,1} + \varphi_{x,2}\varphi_{y,2} + \varphi_{x,3}\varphi_{y,3}$$

- Implicit dot product in F:

$$\Rightarrow x_1^2 y_1^2 + x_2^2 y_2^2 + 2x_1 y_1 x_2 y_2 = (x_1 y_1 + x_2 y_2)^2$$

$$\phi^T(\vec{x}) \cdot \phi(\vec{y}) = k(\vec{x}, \vec{y}) = (\vec{x}^T \cdot \vec{y})^2$$

Kernel trick & dot product

Kernel function

- The implicit form of the dot product in F uses a kernel function $k(\vec{x}, \vec{y})$.
- $k(\vec{x}, \vec{y})$ does not need the evaluation (or knowledge) of $\phi(\vec{x})$ nor $\phi(\vec{y})$.
- Any algorithm using only dot products can be expressed implicitly in F .

Kernel trick & dot product

some classical kernels

- **Gaussian:** $(N_F = \infty)$

$$k(\vec{x}, \vec{y}) = \exp\left(-\frac{\|\vec{x} - \vec{y}\|^2}{\sigma^2}\right)$$

- **Sigmoid:** $(N_F = \infty)$

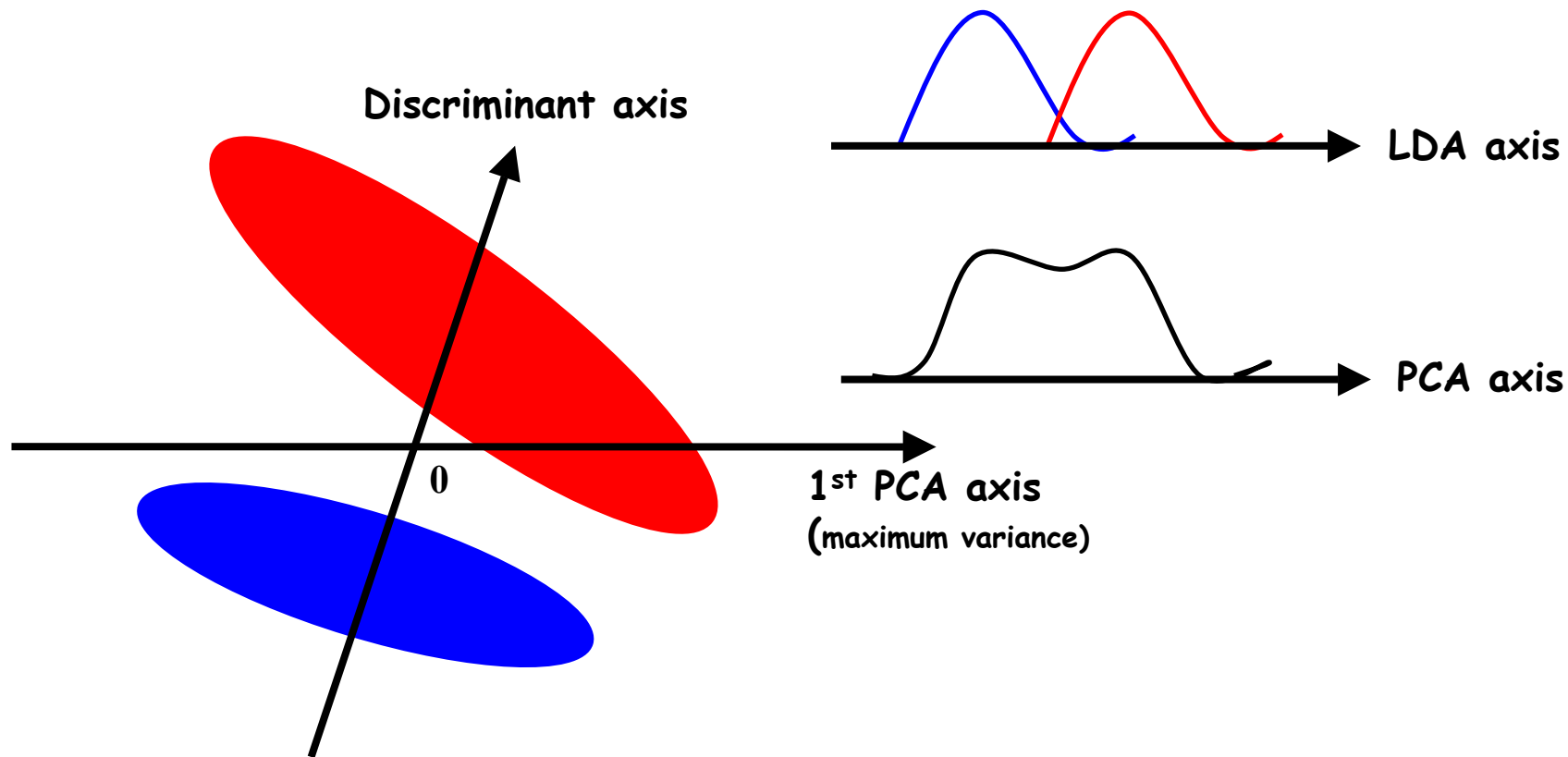
$$k(\vec{x}, \vec{y}) = \tanh(a \vec{x}^T \cdot \vec{y} + b)$$

- **Homogenous polynomial:** $\left(N_F = \frac{(d + N_X - 1)!}{d!(N_X - 1)!}\right)$

$$k(\vec{x}, \vec{y}) = (\vec{x}^T \cdot \vec{y})^d \quad \forall d \in \{1, 2, 3, \dots\}$$

Linear Discriminant Analysis LDA

■ LDA versus PCA projection:



LDA

Classical criterion

- Let's assume N clusters and M samples:
- C : *total covariance matrix*
- G : *covariance matrix of the centers*
- \vec{v}_i : *i^{th} discriminant axis ($i=1, \dots, N-1$)*
- LDA maximizes the variance ratio:

$$\lambda_i = \frac{\text{Inter-class variance}}{\text{Total variance}} \longrightarrow \lambda_i = \frac{\vec{v}_i^T G \vec{v}_i}{\vec{v}_i^T C \vec{v}_i}$$

LDA Resolution

- The solution is based on an eigen system:

$$\lambda_i \vec{v}_i = C^{-1} G \vec{v}_i$$

- The eigen vectors are linear combinations of the learning samples:

$$\vec{v}_i = \sum_{j=1}^M \alpha_{ij} \vec{x}_j$$

Generalized Discriminant Analysis (GDA)

- LDA in the feature space F .
- The eigen vectors are linear combinations of the learning samples:

$$\vec{v}_i = \sum_{j=1}^M \alpha_{ij} \phi(\vec{x}_j)$$

- Consequently any projection becomes:

$$\vec{v}_i^T \cdot \vec{z} = \sum_{j=1}^M \alpha_{ij} k(\vec{x}_j, \vec{z})$$

GDA

Covariance matrixes in F

- We assume the data are centered in F.
- Total covariance matrix:

$$\mathbf{V} = \frac{1}{M} \sum_{j=1}^M \phi(\vec{x}_j) \phi^T(\vec{x}_j)$$

- Covariance matrix of the N centers:

$$\mathbf{B} = \frac{1}{M} \sum_{l=1}^N n_l \bar{\phi}_l \bar{\phi}_l^T \quad \bar{\phi}_l = \frac{1}{n_l} \sum_{k=1}^{n_l} \phi(\vec{x}_{lk})$$

GDA

Resolution

- Let K be the kernel matrix ($M \times M$):

$$K = (k(\vec{x}_i, \vec{x}_j))_{\substack{i=1, \dots, M \\ j=1, \dots, M}}$$

- The LDA criterion in F becomes:

$$\lambda_i = \frac{\vec{\alpha}_i^T K W K \vec{\alpha}_i}{\vec{\alpha}_i^T K^2 \vec{\alpha}_i}$$

where W is a ($M \times M$) bloc diagonal matrix of weights $1/n_l$.

GDA

Resolution (cont.)

- Let's use an eigen decomposition of K :

$$K = U \Gamma U^T$$

- Then by substitution:

$$\lambda_i = \frac{\vec{\beta}_i^T U^T W U \vec{\beta}_i}{\vec{\beta}_i^T \vec{\beta}_i} \quad \text{where } \vec{\beta}_i = \Gamma U^T \vec{\alpha}_i$$

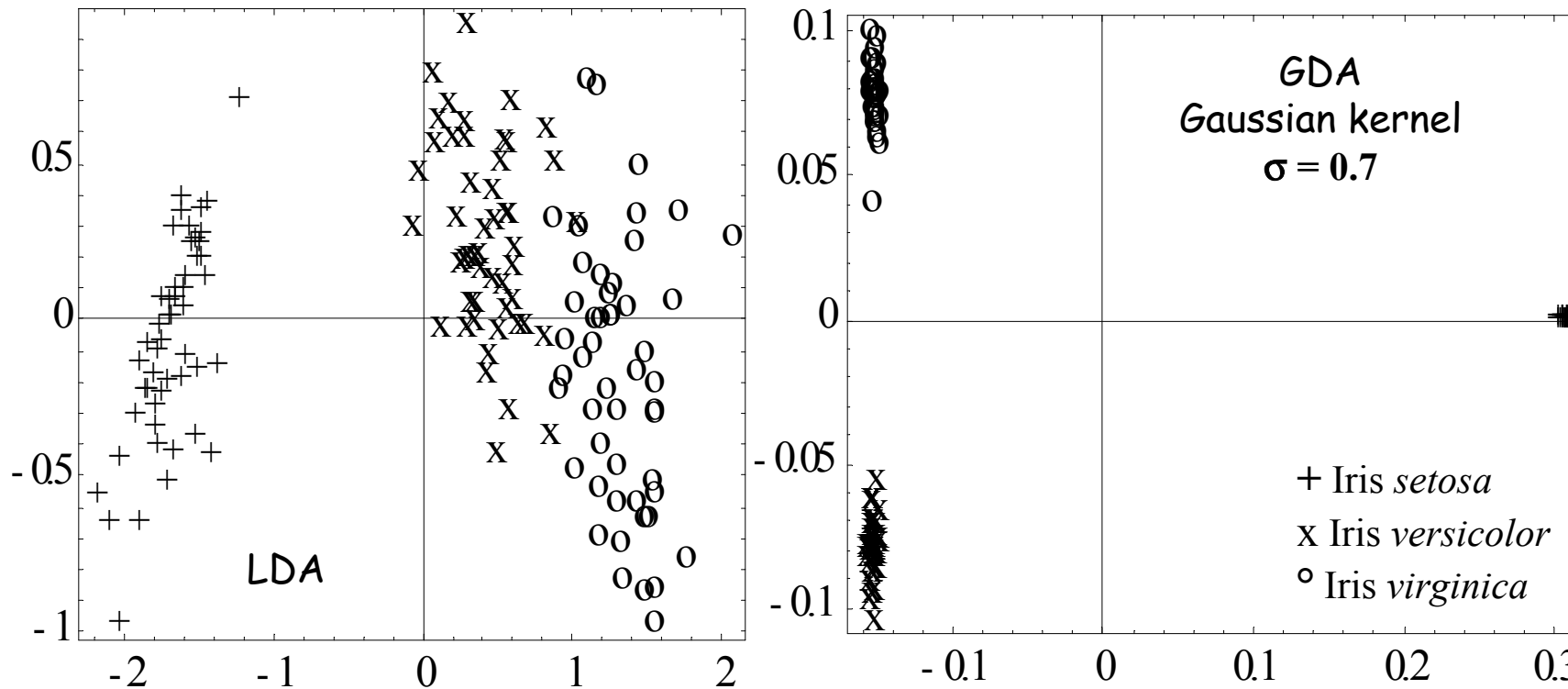
- Finally it is just a classical eigen system:

$$\lambda_i \vec{\beta}_i = U^T W U \vec{\beta}_i$$

GDA

An example

- Fisher's iris data (3 clusters, 4D).

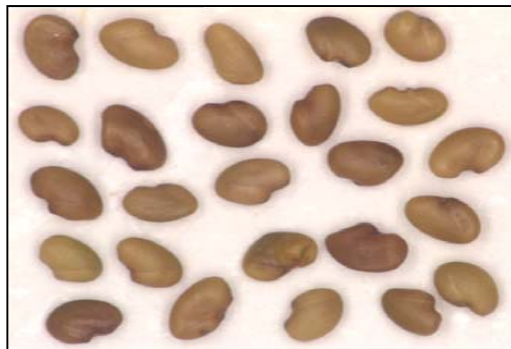


GDA

An application

■ Seed classification (SNES-France)

3 classes: *Medicago sativa* L., *Melilotus* sp & *Medicago lupulina* L



Medicago sativa L



Medicago lupulina L

<i>Methods</i>	<i>Learning error</i>	<i>Test error</i>
LDA	27.2%	32.7%
GDA*	0%	14.9%
Probabilistic NN	0%	14.4%

* Gaussian kernel ($\sigma=0.5$)

GDA

Some comments

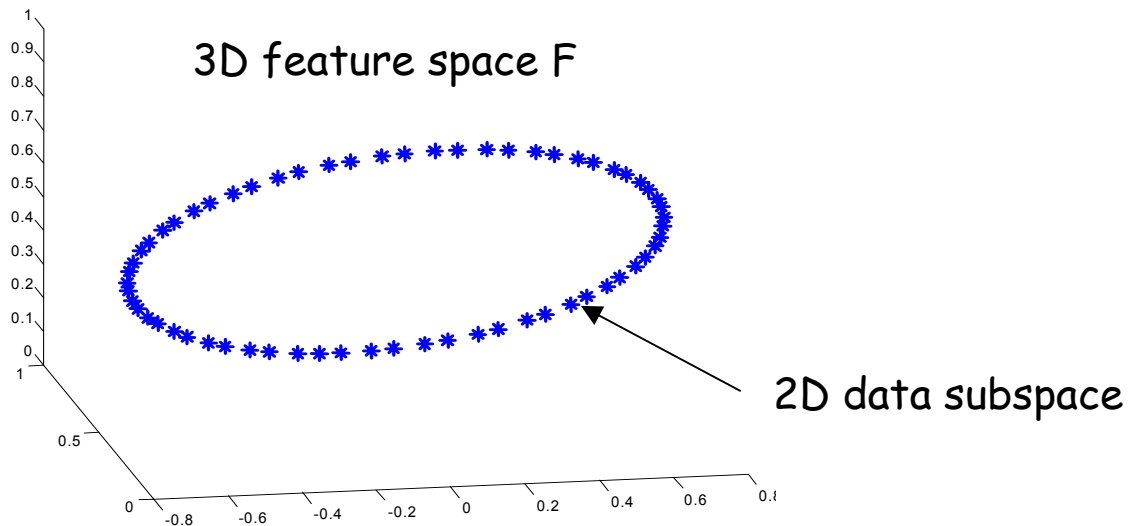
- $k(\vec{x}_i, \vec{x}_j) = \vec{x}_i^T \vec{x}_j$ defines the LDA in X .
- The α_i coefficients are not unique. One possible solution is:

$$\vec{\alpha}_i = U\Gamma^{-1}\vec{\beta}_i$$

- Without special care this leads to a dense expansion for the discriminant axes. Meaning the all M samples are involved.

Feature Vector Selection (FVS)

- Often the data spans a subspace in F with a dimension lower than the size M of the learning data.



- **Idea:** Describe this subspace by L Feature Vectors (FV) taken among the samples. They define a basis S in F , with $L \leq M$.

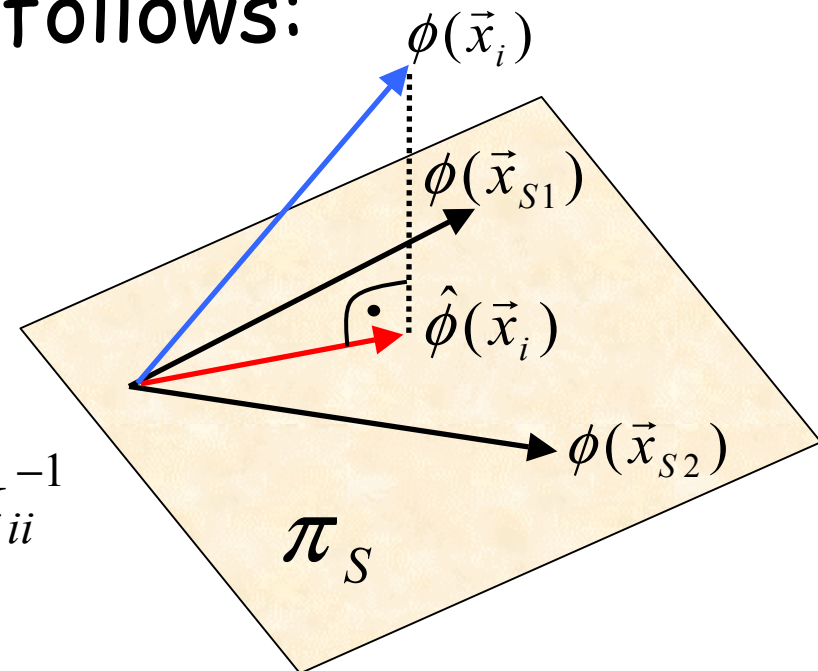
FVS Algorithm

- The FVS is based on a sequential forward selection maximizing a fitness function defined as follows:

$$J_S = \frac{1}{M} \sum_{i=1}^M \frac{\|\hat{\phi}(\vec{x}_i)\|^2}{\|\phi(\vec{x}_i)\|^2}$$

$$J_S = \frac{1}{M} \sum_{i=1}^M \vec{K}_{Si}^T \mathbf{K}_{SS}^{-1} \vec{K}_{Si} k_{ii}^{-1}$$

$$0 \leq J_S \leq 1$$



FVS

Empirical kernel map

- After the FVS we can project any sample using the basis S . This provide new explicit vectors:

$$\vec{K}_{Si} = \left(k(\vec{x}_{S1}, \vec{x}_i), \dots, k(\vec{x}_{SL}, \vec{x}_i) \right)^T$$

- This is known as an empirical kernel map.

FVS

Sparse GDA using FVS

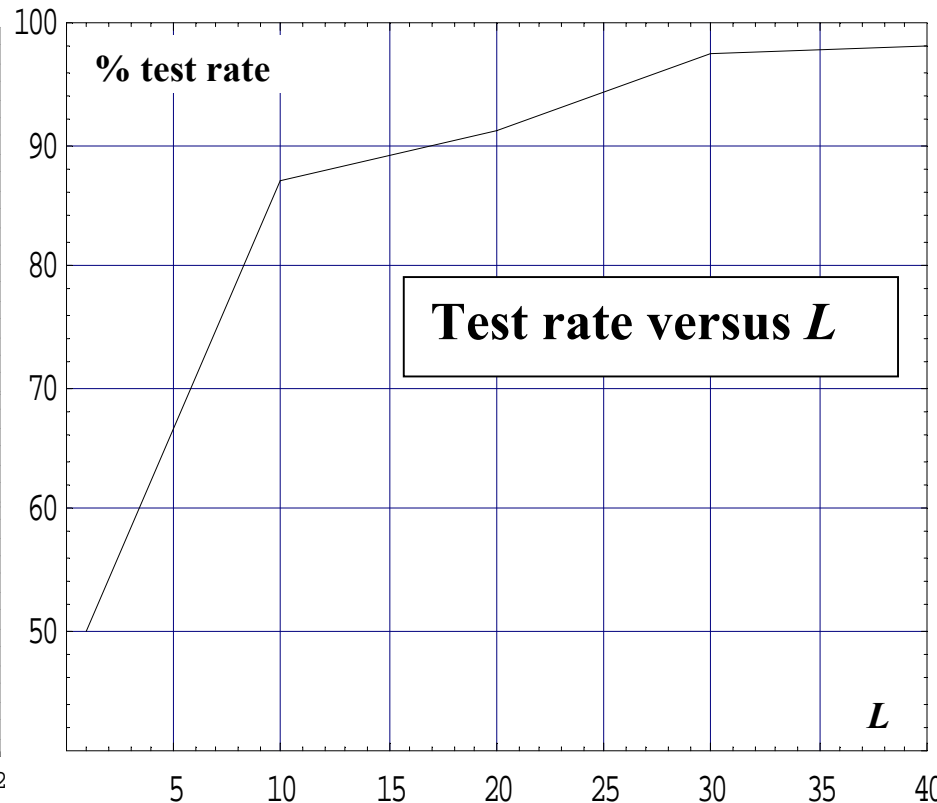
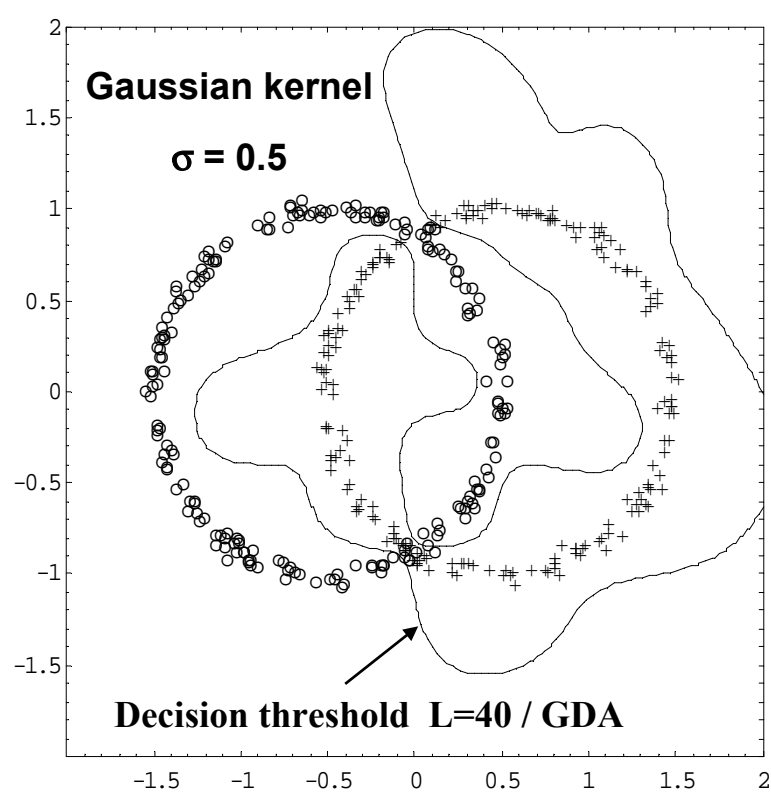
- After the FVS and projection we use the LDA to approximate the GDA.
- Then any projection on a discriminant axis uses an expansion of only L terms:

$$\vec{v}_i^T \cdot \vec{z} = \sum_{j=1}^L \alpha_{ij} k(\vec{x}_{S_j}, \vec{z})$$

FVS-GDA

An example

- 2 clusters ('o' & '+'). 100 samples to learn and 100 others for testing.



Conclusions

- ➔ The GDA allows reusing the LDA approach for non-linear cases.
- ➔ The projection of samples using a non-linear discriminant scheme provides a convenient way to visualize, analyze, and perform other tasks, such as classification with linear methods.
- ➔ Sparse techniques such as FVS overcome the cost of a dense expansion for the discriminant axes.

Some references

- Mika S., Rätsch G., Weston J., Schölkopf B., Müller K. R., **"Fisher Discriminant Analysis with Kernels"**. *Proc. IEEE Neural Networks for Signal Processing Workshop, NNSP, 1999.*
- Mika S., Smola A., Schölkopf B., **"An Improved Training Algorithm for Kernel Fisher Discriminants"**. In *Artificial Intelligence and Statistics*, pages 98-104, San-Fransisco, CA USA, 2001. Morgan Kaufmann.
- Mika S., Rätsch G., Müller K. R., **"A Mathematical Programming Approach to the Kernel Fisher Discriminant"**. In *Advances in Neural Information Processing Systems 13*, 2001 (to appear).
- Schölkopf B., Smola A., **"Learning with Kernels"**. *The MIT press, Cambridge, Massachusetts, 2002.*